규정된 선형 연산자 방정식에 대한 Conjugate gradient 방법에 관하여

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ON THE CONJUGATE GRADIENT METHOD FOR CONSTRAINED SINGULAR LINEAR OPERATOR EQUATIONS

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1. Introuduction

In this paper we introduce the weighted generalized inverse of a linear operator in a general Hilbert space, and we establish the convergence of the conjugate gradient method to the least squares solution of minimal norm.

Throughout this paper, we shall let X, Y, and Z be (real or complex) Hibert spaces, and let A be a bounded linear operator on X into Y. The linear equation

(1) Ax = y for $y \in Y$

may or may not have a solution depending on whether or not y is in R(A), the range of A, and even if $y \in R(A)$ the solution of (1) need not be unique. In either case, one can seek a least squares solution i. e., a solution which minimizes the quadratic functional f $(x) = || Ax-y ||^2$. Such a solution exists for all $y \in R(A) \oplus R(A)^{\perp}$. We shall also be interested in the least squares solution of minimial norm.

We consider the conjugate gradient method that minimizes f(x) at each step. That is, choose an initial vector $x_0 \epsilon$ X, then compute $r_0 = P_0 = A^{\bullet}(Ax_0-y)$, where A^{\bullet} is the adjoint of A. If $p_0 \neq 0$, compute $x_1 = x_0 - \alpha_0 p_0$ where $\alpha_0 = ||r_0||^2 / ||Ap_0||^2$. For $i = 1, 2, \cdots$, compute

(2) $\mathbf{r}_i = \mathbf{A}^*(\mathbf{A}\mathbf{x}_i - \mathbf{y}) = \mathbf{r}_{i-1} - \boldsymbol{\alpha}_{i-1}\mathbf{A}^*\mathbf{A}\mathbf{p}_{i-1},$

where

(3)
$$\alpha_{i-1} = \frac{\langle \mathbf{r}_{n-1}, \mathbf{p}_{n-1} \rangle}{\|\mathbf{A}\mathbf{p}_{i-1}\|^2},$$

and if $r_i \neq 0$, then compute

(4)
$$\mathbf{p}_{i} = \mathbf{r}_{i} + \boldsymbol{\beta}_{i-1} \mathbf{p}_{i-1}$$
, where $\boldsymbol{\beta}_{i-1} = -\frac{\langle \mathbf{r}_{i}, \mathbf{A}^{*} \mathbf{A} \mathbf{p}_{i-1} \rangle}{\| \mathbf{A} \mathbf{p}_{i-1} \|^{2}}$,

and set

(5) $\mathbf{x}_{i+1} = \mathbf{x}_i - \boldsymbol{\alpha}_i \mathbf{p}_i$

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2. Least squares solutions and weighted generalized inverse

For any subspace S, we denote the orthogonal complement of S by S^1 and the closure of S by \bar{s} . Let D(A), R(A), and N(A) denote, respectively, the domain, the range and the null space of a linear operator A. The restriction of A to a set K is denoted by L|K. It is well Known [1]

 $\mathbf{X} = \mathbf{N}(\mathbf{A}) \bigoplus \mathbf{N}(\mathbf{A})^{\perp}$

$$\mathbf{Y} = \mathbf{N}(\mathbf{A}^*) \oplus \mathbf{N}(\mathbf{A}^*)^2$$

 $\{R(T)\}^{\perp} = N(A^{*}), R(A^{*}) = N(A)^{\perp}, R(A) = N(A^{*})^{\perp}.$

For a given $y \in Y$, an element $u \in X$ is called a least squares solution of the linear opeator equation Ax = y if $||Au - y|| \leq ||Ax - y||$ for all $x \in X$. Among least squares solutions an element v of minimal norm is called a best approximate solution of (1). For each $y \in R(A) \oplus R(A)^{\perp}$, the set of all least squares solutions of (1) is a nonempty closed convex subset of X and hence has a unique element v of minimal norm. The generalized inverse A^+ of A is the operator whose domatin is $D(A^+) = R(A) \oplus R(A)^{\perp}$ and $A^+y = v$, where v is the unique best approximate solution of the equation (1). If R(A) is not closed, then A^+ is only densely defined and unbounded. If u is a least squares solution of (1), then $u = A^+y + (I - A^+A)x_0$ for some $x_0 \in X$.

Let L be a bounded linear operator from X into Z. We assume that the range R(L) of L is closed in Z, but the range R(A) of A is not necessarily closed in Y. For a given y in $D(A^+)$, let

(6) $\mathbf{S}_{\mathbf{y}} = \{ \mathbf{u}\boldsymbol{\varepsilon} \ \mathbf{X} : \| \mathbf{A}\mathbf{u} - \mathbf{y} \|_{\mathbf{y}} = \inf \| \mathbf{A}\mathbf{x} - \mathbf{y} \|_{\mathbf{y}}, \ \mathbf{x}\boldsymbol{\varepsilon} \ \mathbf{X} \}.$

Then the problem is to find we S_y such that

(7) $\| \mathbf{Lw} \|_{\mathbf{z}} = \inf\{ \| \mathbf{Lu} \|_{\mathbf{z}} : \mathbf{u} \in \mathbf{S}_{\mathbf{y}} \}.$

The problem (6)-(7) has a solution for every $y \in D(A^+)$ if and only if N(A) + N(L) is closed, and the solution is unique if and only if $N(A) \cap N(L) = \{0\}$. Throughout this paper, we assume that $N(A) \cap N(L) = \{0\}$ and N(A) + N(L) is closed.

We define a new inner product in X :

 $(\mathbf{u}, \mathbf{v}) = \langle \mathbf{A}\mathbf{u}, \mathbf{A}\mathbf{v} \rangle_{Y} + \langle \mathbf{L}\mathbf{u}, \mathbf{L}\mathbf{v} \rangle_{Z}$ for $\mathbf{u}, \mathbf{v} \boldsymbol{\varepsilon} \mathbf{X}$.

We denote the space X with the inner product $[\cdot, \cdot]$ by X_{L} .

THEOREM 1. An element we X is a solution to the problem $(6)\mathchar`-(7)$ if and only if $A^*Aw\!=\!A^*y$ and $L^*Lw\epsilon\ N(A)$.

Proof. Refer to Nashed[2].

The solution w is the least squares solution of X_L -minimal norm of the equation (1). Let A^+_L denote the map induced by $y \to w$ and call it the weighted generalized inverse of A.

3. Regularization and some observations on the conjugate gradient method

When the range of A is closed, the problem (6) - (7) is well-posed. Hence our interest is in the case that the range of A is not closed and hence the problem is ill-posed. Instead of solving this ill-posed problem directly, we will regularize it by a family of stable minimization problems.

Let W be the product space of Y and Z with the usual inner product :

$$\begin{split} W &= Y \times Z, \\ \langle (y_1, z_1), \langle (y_2, z_2) \rangle_W &= \langle y_1, y_2 \rangle_Y + \langle z_1, z_2 \rangle_Z \end{split}$$

for $y_1, y_2 \varepsilon$ Y and $z_1, z_2 \varepsilon$ Z.

For $\alpha > 0$, let $C\alpha$ be a linear operator from X into W defined by $C\alpha \mathbf{x} = (A\mathbf{x}, \mathbf{v}_{\alpha})$ Lx) for $\mathbf{x} \in X$. We denote by U_{α} the unique best approximate solution of the equation $C_{\alpha}\mathbf{x} = \tilde{\mathbf{y}}$ for each $\mathbf{x} > 0$ where $\tilde{\mathbf{y}} = (\mathbf{y}, 0)$ in W. That is, $U_{\alpha} = C_{\alpha}^{+}\mathbf{y}$. Let us write $J_{\alpha}(\mathbf{x}) = \|\mathbf{A}\mathbf{x}-\mathbf{y}\|^{2} + \alpha \|\|\mathbf{L}\mathbf{x}\|\|^{2}$.

THEOREM 2. Let $\alpha > 0$. An element $X_{\dot{\alpha}}$ in X minimizes the quadratic functional $J_{\alpha}(x)$ if and only if $C^*_{\alpha} C_{\alpha} x = C^*_{\alpha} y$.

Proof. It is easy and omitted.

 $\| X \|$ and $\| X \|_{L}$ are equivalent if AN(L) is closed. Throughout this paper we assume that AN(L) is closed.

THEOREM 3. For $\alpha > 0$, let U α be the unique solution of the operator equation (8). Then $\lim_{\alpha \to 0} U_{\alpha}$ exists and $\lim_{\alpha \to 0} U_{\alpha} = A^{+}_{L}y$.

Proof. Refer to Song [3].

We now examine some properties of the conjugate gradient algorithm described in the introduction. Let P denote the orthogonal projection of X onto $\overline{R(C_{*})}$ and let Q denote the orthogonal projection of W onto $\overline{R(C_{*})}$. If $\tilde{y} \in D(C_{*}^{+})$, then $Q\tilde{y} = \tilde{y} \in R(C_{*})$ and $v = C_{*}^{+} \tilde{y} = C_{*}^{+} \tilde{y}$ and $\tilde{y} = Q\tilde{y} = C_{*} v = C_{*}^{-} C_{*}^{+} \tilde{y}$. Since Q is an orthogonal projection, the functional $J_{*}(x)$ can be written as $J_{*}(x) = ||C_{*}x-y||^{2} = ||C_{*}|$

 $x-\hat{y} \parallel ^{2} + \parallel \hat{y}-y \parallel ^{2}$. Thus, minimizing $J_{o}(x)$ is equivalent to minimizing the functional $\parallel C_{o}x-\hat{y} \parallel ^{2}$ which we shall denote by $K_{*}(X)$.

Setting $u=v+(I-P)x_0=C_a^*y+(I-P)x_0$. One can define the error vector e=x-u and the vector $r=C_a^*(C_ax-\hat{y})=C_a^*(C_ax-\hat{y})$

Then $(C_{a}^{*}C_{a})e=r$ and $[r, e] = ||C_{a}x-\hat{y}||^{2} = K_{a}(x)$.

The sequence of iterates $\{\mathbf{x}_i\}$ generated by the conjugate gradient method $(2) \cdot (5)$ is contained in $\mathbf{x}_0 + \mathbb{R}(\mathbb{C}^{\bullet}_a)$ with both \mathbf{r}_i and \mathbf{p}_i , for $i=0, -1, -2, \cdots$, in $\mathbb{R}(\mathbb{C}^{\bullet}_a)$. Unless explicitly mentioned otherwise, we shall assume that the conjuate gradient method does not terminate in a finite number of steps, that is $\mathbf{r}_i \neq 0$ for $i=0, -1, -2, \cdots$.

We shall make use of the following lemmas.

Lemma 4. (a) For k=0, 1, 2, ..., i $K\alpha(x_i) = [r_i, e_k] = [e_i, r_k]$

(b) For i=0, 1, 2,, $[p_i, e_i] \parallel r_i \parallel^2 = K \alpha (x_i) \parallel p_i \parallel^2$.

Proof. Refer to Kammerer [4]

Lemma 5. The inequality $||| e_{i+i} |||^2 \leq ||| e_i |||^2 - \alpha_i K \alpha(\mathbf{x}_i)$ holds for $i = 0, 1, 2, \cdots$. Proof. Making use of Lemma 4(b), we get the following sequence of identities:

$$\| \mathbf{e}_{i+1} \|^{2} = \| \mathbf{e}_{i} \|^{2} - 2\alpha_{i} [\mathbf{e}_{i}, \mathbf{p}_{i}] + \alpha_{i}^{2} \| \mathbf{p}_{i} \|^{2}$$

$$= \| \mathbf{e}_{i} \|^{2} - \alpha_{i} \{ 2\mathbf{K}\alpha_{i} (\mathbf{x}_{i}) - \alpha_{i} \| \mathbf{r}_{i} \|^{2} \} \frac{\| \mathbf{p}_{i} \|^{2}}{\| \mathbf{r}_{i} \|^{2}}$$

$$= \| \mathbf{e}_{i} \|^{2} - \alpha_{i} \{ \mathbf{K}\alpha_{i} (\mathbf{x}_{i}) + \mathbf{K}\alpha_{i+i}) \} \frac{\| \mathbf{p}_{i} \|^{2}}{\| \mathbf{r}_{i} \|^{2}}$$

$$\leq \| \mathbf{e}_{i} \|^{2} - \alpha_{i} \mathbf{K}\alpha_{i} (\mathbf{x}_{i}) .$$

Lemma 6. For any nonnegative integers i and j, both $[p_i,e_i]$ and $[e_i,e_j]$ are nonnegative.

Proof. Lemma 4 (b) shows that $[p_i,e_i]$ is nonnegative. To show that $[e_i,e_j]$ is nonnegative, we shall assume without loss of generality that $i \ge j$. Then $e_j = e_i + \alpha_{i-1}$

 $\mathbf{p}_{i-1}^{+}\cdots^{+}\boldsymbol{\alpha}_{j}\mathbf{p}_{j}$, and $[\mathbf{e}_{i},\mathbf{e}_{j}] = [\mathbf{e}_{i},\mathbf{e}_{i}] + \sum_{k=j}^{i-1} \boldsymbol{\alpha}_{k}[\mathbf{e}_{i},\mathbf{p}_{k}]$, which is nonnegative.

4. Convergence of the conjugate gradient method.

In this section, using the conjugate gradient method, we find an approximate solution U α of the regularized operator equation $C^*_{\alpha}C_{\alpha}x = C^*_{\alpha}\bar{y}$.

We prove the convergence of the conjugate gradient method to a solution of $C^*_{\alpha}C_{\alpha}x = C^*_{\alpha}y$.

THEOREM 7. In the assumptions of section 2-3, the conjugate gradient method (2)

-(5) converges monotonically to the least squares solution $u = C_{\sigma}^* \bar{y} + (I-P) x_0$ of $C_{\sigma} x = \bar{y}$. Proof. Refer to [5].

Lemma 8. If $Q\bar{y}\epsilon R(C_aC_a^*)$, then for $i=0, 1, 2, \dots$,

(a) $|| z_{i+1} - \bar{z} || \le || z_i - \bar{z} || \le || z_0 - \bar{z} ||$,

(b) $\| \mathbf{e}_i \|^2 \leq \mathbf{K}_{\mathfrak{a}}(\mathbf{x}_i) \| \mathbf{z}_{\mathrm{O}} \cdot \mathbf{\bar{z}} \|^2$

and

(c) $\| \mathbf{e}_{i+1} \|^2 \leq (1 - B \| \mathbf{e}_i \|^2) \| \mathbf{e}_i \|^2$

where $B = || z_0 - \bar{z} ||^2 || C_a ||^{-2}$.

Proof. (a). (5) imply that $z_i z_{i+1} = \alpha_i v^{-1} p_i$ for $i = 0, 1, 2, \dots$, where $U = C_a^* \mid R(C_a^*)$

$$\| z_{i+1} - \bar{z} \|^{2} = \| z_{i} - \bar{z} \|^{2} - 2\alpha_{i} [U^{-1}p_{i}, z_{i} - \bar{z}] + \alpha^{2}_{i} \| U^{-1}p_{i} \|^{2}$$

$$= \| z_{i} - \bar{z} \|^{2} - \alpha_{i} \{ 2[U^{-1}p_{i}, iz_{i} - \bar{z}] - [U^{-1}p_{i}, z_{i} - z_{i+1}] \}$$

$$= \| z_{1} - \bar{z} \|^{2} - \alpha_{i} [U^{-1}p_{i}, (z_{i} - \bar{z}) + (z_{i+1} - \bar{z})]$$

$$= \| z_{i} - \bar{z} \|^{2} - \alpha_{i} [U^{-1}p_{i}, v^{-1}(e_{i} + e_{i+1})]$$

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=
$$|| z_i - \overline{z} ||^2 - \alpha_i [v^{-1}u^{-1}p_i, e_i + e_{i+1}]$$
 where $V = C\alpha || R(C^*)$

Therefore, we need only show that $[v^{-1}u^{-1}p_i, e_i + e_{i+1}]$ is nonnegative.

$$[\mathbf{v}^{-1}\mathbf{u}^{-1}\mathbf{p}_{i}, \mathbf{e}_{i} + \mathbf{e}_{j}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \| \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{v}^{-1}\mathbf{u}^{-1}\mathbf{r}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{e}_{\mathbf{k}}, \mathbf{e}_{i} + \mathbf{e}_{i+1}] = \| \mathbf{r}_{i} \|^{2} \sum_{\mathbf{k}=0}^{i} \frac{1}{\| \mathbf{r}_{\mathbf{k}} \|^{2}} [\mathbf{r}_{i} \|^{2} \mathbf{e}_{i} \|^{2}} [\mathbf{r}_{i} \|^{2} \mathbf{e}_{i} \|^{2$$

 $e_{i+1}],$

which by Lemma 6 is nonnegative.

(b) Using the Cauch-Schwarz inequality and part (a), we obtain $||e_i||^2 = |[\mathbf{x}_i - \mathbf{u}, \mathbf{C}^* \mathbf{z}_i - \mathbf{u}]|^2 = |[\mathbf{C}_{\overline{a}}(\mathbf{x}_i - \mathbf{u}), \mathbf{z}_i - \overline{\mathbf{z}}]|^2 \leq \mathbf{k}_{a}(\mathbf{x}_i) ||\mathbf{z}_0 - \overline{\mathbf{z}}||^2$.

(c) The boundedness of C_{α} show that

(9)
$$\boldsymbol{\alpha}_{i} = \frac{\|\mathbf{r}_{i}\|^{2}}{\|\mathbf{C}_{\sigma}\mathbf{p}_{i}\|^{2}} \ge \frac{\|\mathbf{r}_{i}\|^{2}}{\|\mathbf{C}_{\sigma}\mathbf{r}_{i}\|^{2}} \ge \frac{1}{\|\mathbf{C}_{\sigma}\|^{2}}$$

Part (C) is established by using of Lemma 5 and 8 (b) and (9) in the following manner :

$$\| \mathbf{e}_{i+1} \|^{2} \leq \| \mathbf{e}_{i} \|^{2} - \boldsymbol{\alpha}_{i} \mathbf{K} \boldsymbol{\alpha}_{i}(\mathbf{x}_{i}) \leq \| \mathbf{e}_{i} \|^{2} - \frac{\boldsymbol{\alpha}_{i} \| \mathbf{e}_{i} \|^{4}}{\| \mathbf{z}_{0} - \mathbf{z} \|} \leq (1 - \frac{\| \mathbf{e}_{i} \|^{2}}{\| \mathbf{z}_{0} - \mathbf{z} \|^{2} \| \mathbf{C}_{a} \|^{2}}) \| \mathbf{e}_{i} \|^{2}.$$

LEMMA 9. If the sequence $\{C_i\}$ of real numbers satisfies

 $0 \le C_{i+1} \le (1-BC_i)C_i$, i=0, 1, 2,, with B>0 and $0 < BC_0 \le 1$ then

(10) $C_i \leq \frac{C_0}{1+iBC_0}$ for $i = 0, 1, 2, \dots$

Proof. If $C_i = 0$, then $C_{i+n} = 0$ for $n = 0, -1, -2, \dots$. Therefore, without loss of generality, we shall assume that $C_i > 0$ for all i.

The inequality $C_{k+1} < C_k$ for $k=0, 1, 2, \cdots$, cna be established easily by induction. Then, summing the inequalities $\frac{1}{C_{k+1}} - \frac{1}{C_k} = \frac{C_k - C_{k+1}}{C_k C_{k+1}} \ge \frac{BC^2_k}{C_k C_{k+1}} > B$ from k=0 to k=i-1

yields $\frac{1}{C_i} - \frac{1}{C_0} > iB.$

Inequality (10) results when this inequality is solved for C_i .

THEOREM 10. If $Q\bar{y}\epsilon R(C_{\alpha}C_{\alpha}^{*}C_{\alpha})$, then the conjugate gradient method (2)-(5), with initial value $x_{0}\epsilon R(C_{\alpha}^{*}C_{\alpha})$, converges monotonically to the best approximate solution $u_{\alpha} = C_{\alpha}^{*}\bar{y}$. In fact

(11)
$$\| \mathbf{x}_{i} - \mathbf{u}_{a} \|^{2} \leq$$

$$\frac{\| C_{a} \|^{2} \| \mathbf{x}_{0} - C_{a}^{*} \bar{\mathbf{y}} \|^{2} \| (C_{a}^{*})^{+} \mathbf{x}_{0} - (C_{a} C_{a}^{*})^{+} \bar{\mathbf{y}} \|^{2}}{\| C_{a} \|^{2} \| (C_{a}^{*})^{+} \mathbf{x}_{0} - (C_{a} C_{a}^{*} \bar{\mathbf{y}})^{+} \bar{\mathbf{y}} \|^{2} + \mathbf{i} \| \mathbf{x}_{0} - C_{a}^{*} \bar{\mathbf{y}} \|}$$

$$\mathbf{i} = 1, 2, \cdots$$

Proof. From Lemma 8(c), $||| e_{i+1} |||^2 \leq (1-B ||| e_i |||^2) ||| e_i |||^2$,

where $B = || z_0 - \bar{z} || - 2 || C_a || - 2$ holds for $i = 0, 1, 2, \cdots$ and

 $B \parallel e_0 \parallel {}^2B \parallel x_0 - u_a \parallel {}^2 = B \parallel C_a^* (z_0 - \bar{z}) \parallel {}^2 \leq \parallel C_a^* \parallel {}^2 \parallel C_a \parallel {}^{-2} = 1$. Lemma 9 can now be applied to this difference inequality showing that

 $\| e_i \|^2 \leq \frac{\| \mathbf{x}_0 - \mathbf{u}_{\mathfrak{a}} \|^2}{|\mathbf{i} + \mathbf{i}B \| \| \mathbf{x}_0 - \mathbf{u}_{\mathfrak{a}} \|^2}$

Inequality (11) results when $x_0^-u_a$ is replaced by $x_0^-C^+\bar{y}$ and relation $z = (C_a C_a^*)^+ y$ is utilized. This completes the proof of Theorm 10.

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본 논문에서는 Weighted generalized inverse 를 소개하고 Conjugate gradient 방법에 의해 형성되는 수열은 최적 근사치 해에 수렴한다는 것을 보이고 오차 범위를 결정하 였다.