On the Volume of an N-Surface

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감사의 글

이 논문이 완성되기 까지 바쁘신 가운데도 자세한 지도 를 하여 주신 현진오 교수님께 감사드리며, 그동안 많은 도 움을 주신 수학 교육과의 모든 교수님께 심심한 사의를 표합니다. 아울러 그동안 저에게 사랑과 격려를 아끼지 않으신 주위의 많은 분들께 감사드립니다.

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국 문 초 록

- n차 곡면의 체적에 관하여
 - 제주대학교교육대학원



본 논문의 목적은 Level Set의 정의를 사용하여 곡면 의 호의 길이,면적,체적에 관한 몇가지 성질들을 연구하 는 것이다.

1. INTRODUCTION

We can introduce the properties of the volume of an n-surface in \mathbb{R}^{n+1} by using well-known definition.

In this paper, we begin with defining a volume of an n-surface in \mathbb{R}^{n+1} on the definition of a level set. Then we will prove the properties of the arc length, area and volume of an n-surface in \mathbb{R}^{n+1} according to its definition.

For our further discussion, several definitions and notations will be given first of all.

2. DEFINITION AND NOTATION

Given a function $f: U \to R$, where U is an open subset in \mathbb{R}^{n+1} .

DEFINITION(2.1). Level sets are the sets $f^{-1}(C)$ defined by $f^{-1}(C) = \{(x_1, x_2, \dots, x_{n+1}) \in (\bigcup | f(x_1, x_2, \dots, x_n) = C\}$ for each real number C. The number C is called the height of the level set and $f^{-1}(C)$ is called the level set at height C.

DEFINITION(2.2). A vector field **X** on $U \subseteq \mathbb{R}^{n+1}$ is a function which assigns to each point of U a vector at that point. Thus $\mathbf{X}(p) = (p, X(p))$ for some function $X: U \to \mathbb{R}^{n+1}$.

DEFINITION(2.3). A parametrized curve $\alpha: I \to \mathbb{R}^{n+1}$ is said to be an integral curve of the vector field **X** on the open

set U in \mathbb{R}^{n+1} if $\alpha(t) \in U$ and $\dot{\alpha}(t) = X(\alpha(t))$ for all $t \in I$.

DEFINITION(2.4). The lenght $\|\dot{a}\|: I \to R$ defined by $\|\dot{\alpha}\|(t) = \dot{\alpha}(t)\|$ along for all $t \in I$ is called the speed of α .

DEFINITION(2.5). A smooth unit normal vector field on an n-surface S in \mathbb{R}^{n+1} is called an orientation on S.

PROPOSITION(2.6). The length of a connected oriented plane curve C can be computed from the formular;

 $\ell(C) = \ell(\alpha) = \int_{a}^{b} \dot{\alpha}(t) dt$, where a, b are the end points of I. **PROPOSITION(2.7)**. If $\beta: \tilde{I} \to \mathbb{R}^{n+1}$ is a reparametrization of α , then $\ell(\alpha) = \ell(\beta)$.

DEFINITION(2.8). A parametrized n-surface in $\mathbb{R}^{n+k}(k \ge 0)$ is a smooth map $\varphi: U \to \mathbb{R}^{n+k}$, where U is a connected open set in \mathbb{R}^n , which is regular; i.e. which is such that $d\varphi_p$ is a nonsingular(has rank n) for each $P \in U$.

DEFINITION(2.9) Let $\varphi: U \to \mathbb{R}^{n+k}$ be any smooth map, U open in \mathbb{R}^n . Then \mathbf{E}_i ($i \in \{1, \dots, n\}$) denote the tangent vector fields along φ defined by $\mathbf{E}_i(p) = (p, 0, \dots, 1, \dots, 0)$, where the 1 is in the (i+1)-th spot.

PROPOSITION(2.10). The components of E_i are the entries in the i-th column of the Jacobian matrix for φ at p:

 $\mathbf{E}_{i}(\mathbf{p}) = (\varphi(\mathbf{p}), \frac{\partial \varphi}{\partial u_{i}}(\mathbf{p})) = (\varphi(\mathbf{p}), \frac{\partial \varphi_{i}}{\partial u_{i}}(\mathbf{p})), \dots, (\frac{\varphi_{n+k}}{U_{i}}(\mathbf{p})), \psi_{i}$ where $\varphi(\mathbf{p}) = (\varphi_{i}(\mathbf{p}), \dots, \varphi_{n+k}(\mathbf{p}))$ for $\mathbf{p} \in U$.

PROPOSITION(2.11). The E_i are called the coordinate vector field along φ_i .

PROPOSITION(2.12). Suppose that $\varphi: U \to \mathbb{R}^{n+1}$ is a parametrized n-surface in \mathbb{R}^{n+1} . Let N(p) denote the unique vector at $\varphi(p)$ such that $N(p) \perp \text{image } d\varphi_p$ and

det
$$\begin{bmatrix} \mathbf{E}(\mathbf{p}_{i}) \\ \mathbf{E}(\mathbf{p}_{i}) \\ \vdots \\ \mathbf{E}(\mathbf{P}_{n}) \\ \mathbf{N}(\mathbf{p}) \end{bmatrix} > 0 \text{ for } \mathbf{p} \in U.$$

Then N is a smooth unit normal vector field along φ .

3. VOLUME OF AN N-SURFACE

In the present section, we prove the properties of the volume of an n-surface in \mathbb{R}^{n+1} with its definition.

We begin by defining the volume of an n-surface.

DEFINITION(3.1) The volume of a parametrized n-surface $\varphi: U \rightarrow \mathbb{R}^{n+1}$ is defined by

$$\nabla(\varphi) = \int_{\mathbf{u}} \det \begin{bmatrix} \mathbf{E}_{1} \\ \mathbf{E}_{2} \\ \vdots \\ \mathbf{E}_{n} \end{bmatrix} = \int_{\mathbf{u}} \det \begin{bmatrix} \mathbf{E}_{1}(u_{1}, \dots, u_{n}) \\ \mathbf{E}_{2}(u_{1}, \dots, u_{n}) \\ \vdots \\ \mathbf{E}_{n}(u_{1}, \dots, u_{n}) \\ \mathbf{N} \end{bmatrix} du_{1}, \dots du_{n}$$

where $\mathbf{E}_{I}, ..., \mathbf{E}_{n}$ are the coordinate vector field along φ and N is the orientation vector field along φ .

In the next theorem, using the above definition, we obtain a formular for volume which does not require calculation of the orientation vector field N.

THEOREM(3.2) Let $\varphi: U \to \mathbb{R}^{n+1}$ be a parametrized n-surface Then $\bigvee (\varphi) = \int_{U} \det \begin{pmatrix} \mathbf{E}_{i} \\ \mathbf{E}_{2} \\ \vdots \\ \mathbf{E}_{n} \end{pmatrix} = \int_{U} \sqrt{\det(\mathbf{E}_{i} \cdot \mathbf{E}_{j})}$. **PROOF.** Using the definition(3.1),

$$\begin{bmatrix} \mathbf{E}_{I} \\ \mathbf{E}_{2} \\ \vdots \\ \mathbf{E}_{n} \\ \mathbf{N} \end{bmatrix}^{2} = \det \begin{bmatrix} \mathbf{E}_{I} \\ \mathbf{E}_{2} \\ \vdots \\ \mathbf{E}_{n} \\ \mathbf{N} \end{bmatrix} (\mathbf{E}_{I}^{t}, \mathbf{E}_{2}^{t}, \cdots \mathbf{E}_{n}^{t}, \mathbf{N}^{t})$$

$$= \det \begin{bmatrix} \mathbf{E}_{1} \cdot \mathbf{E}_{1} \cdots \mathbf{E}_{1} \cdot \mathbf{E}_{n} & 0 \\ \mathbf{E}_{2} \cdot \mathbf{E}_{1} \cdots \mathbf{E}_{2} \cdot \mathbf{E}_{n} & 0 \\ \vdots & \vdots \\ \mathbf{E}_{n} \cdot \mathbf{E}_{1} \cdots \mathbf{E}_{n} \cdot \mathbf{E}_{n} & 0 \\ 0, \dots & 0 \end{bmatrix} = \det(\mathbf{E}_{j} \cdot \mathbf{E}_{j})$$

where \mathbf{E}_i^t is the transpose of \mathbf{E}_i and i, $j \in \{1, 2, \cdots, n\}$.

The formular for the lenght of a parametrized curve $\alpha: I \to \mathbb{R}^2$ can be rewritten as follows.

THEOREM(3.3) The length of a parametrized curve $\alpha: I \to \mathbb{R}^2$ is $\ell(\alpha) = \int_I \|\dot{\alpha}\| = \int_I \det \left(\begin{array}{c} \mathbf{E}_I(t) \\ \mathbf{N}(t) \end{array} \right)$, where α is regular and \mathbf{N} is the orientation vector field along α .

PROOF. Since the velocity field α is the coordinate vector field \mathbf{E}_{I} along the parametrized 1-surface α in \mathbb{R}^{2} and the vector $\mathbf{E}_{I}(t) / ||\mathbf{E}_{I}(t)||$, N form an orthogonal basis for the vector space $\mathbf{R}_{\alpha(t)}^{2} = ||\mathbf{e}_{I}(t)|| \det \left[\frac{\mathbf{E}_{I}(t) / ||\mathbf{E}_{I}(t)||}{\mathbf{N}(t)} \right] = \det \left[\frac{\mathbf{E}_{I}(t)}{\mathbf{N}(t)} \right]$ By definition(3.1), when n = 1, the volume of φ is the length of φ . Moreover, when n = 2, the volume of φ is the area of φ .

Using the above theorem, we obtain a useful theorem.

THEOREM(3.4) Let C be a connected oriented plane curve and \tilde{c} be the same curve with opposite orientation.

Then $\ell(C) = \ell(\overline{C})$

PROOF. Consider parametrized curve $\alpha: I \to C$ oriented by N and $\tilde{\alpha}: \tilde{I} \to \tilde{C}$ oriented by -N.

Then $\int_{I} \det \left[\frac{\mathbf{E}_{I}}{\mathbf{N}} \right] = \int_{\widetilde{I}} \det \left[\frac{\mathbf{E}_{I}}{-\mathbf{N}} \right]$

Using the definition(3.1) and the theorem(3.2), we have the following theorem. 제주대학교 중앙도서관

THEOREM(3.5) Let \mathbf{E}_i be the n-ply orthogonal system along φ . If a function $f: U \to R$ is a smooth function on the open set $U \subseteq R^n$ and $f: U \to R^{n+1}$ is defined by $\varphi(u_1, \dots, u_n) = (u_1, \dots, u_n, f(u_1, \dots, u_n))$, then the volume of φ may be expressed in the integral of

$$\sqrt{1+\sum_{i=1}^{n}(\frac{\partial f}{\partial u_{i}})^{s}}$$
 along φ on U.

PROOF. Since $\mathbf{E}_{i}(p) = (p, \frac{\partial \varphi}{\partial u_{i}}(p)) = (p, 0, \dots, 1, \dots, 0, \frac{\partial f}{\partial u_{i}})$ for $p = (u_{1}, u_{2}, \dots, u_{n}) \in U$,

$$\mathbf{E}_{i} \cdot \mathbf{E}_{j} = \begin{cases} 1 + (\frac{\partial \mathbf{f}}{\partial u_{i}})^{s} & \text{if } i = j \\ \frac{\partial \mathbf{f}}{\partial u_{i}} \cdot \frac{\partial \mathbf{f}}{\partial u_{j}} = 0 & \text{if } i \neq j \end{cases}$$

Hence

$$det(\mathbf{E}_{i} \cdot \mathbf{E}_{j}) = \left[1 + \left(\frac{\vartheta f}{\vartheta u_{i}}\right)^{2}\right] \left[1 + \left(\frac{\vartheta f}{\vartheta u_{2}}\right)^{2}\right] \cdots \left[1 + \left(\frac{\vartheta f}{\vartheta u_{n}}\right)^{2}\right]$$
$$= 1 + \sum_{i=1}^{n} \left(\frac{\vartheta f}{\vartheta u_{i}}\right)^{2}.$$



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ABSTRACT

ON THE VOLUME OF AN N-SURFACE

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The purpose of the present paper is to study some properties of the arc length, area and volume of surface by using definition of level set.